



Parallel Hardware

Part 2

Lecture Objectives:

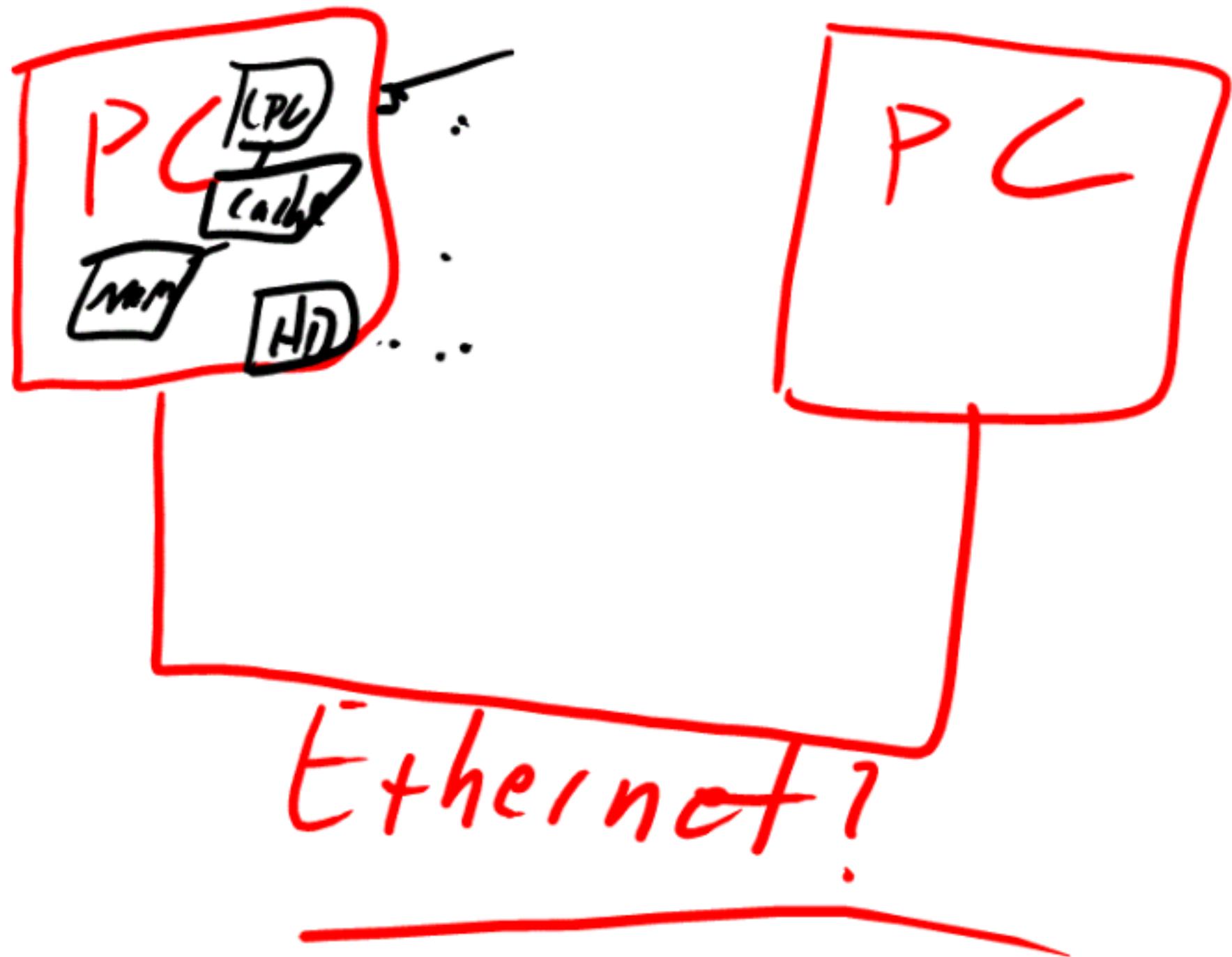
- 1) Compare and contrast a shared memory system with a distributed memory system from an architectural standpoint
- 2) Compare and contrast NORMA, NUMA, and UMA multicore systems
- 3) Draw a picture of a switched interconnect topology using a crossbar connection
- 4) Explain the concepts of a ring, a toroidal mesh, bisected ring, fully connected network, and hypercube architecture.
- 5) Define the terms latency and bandwidth, and explain the implication on parallel computing.

Reading Quiz Question

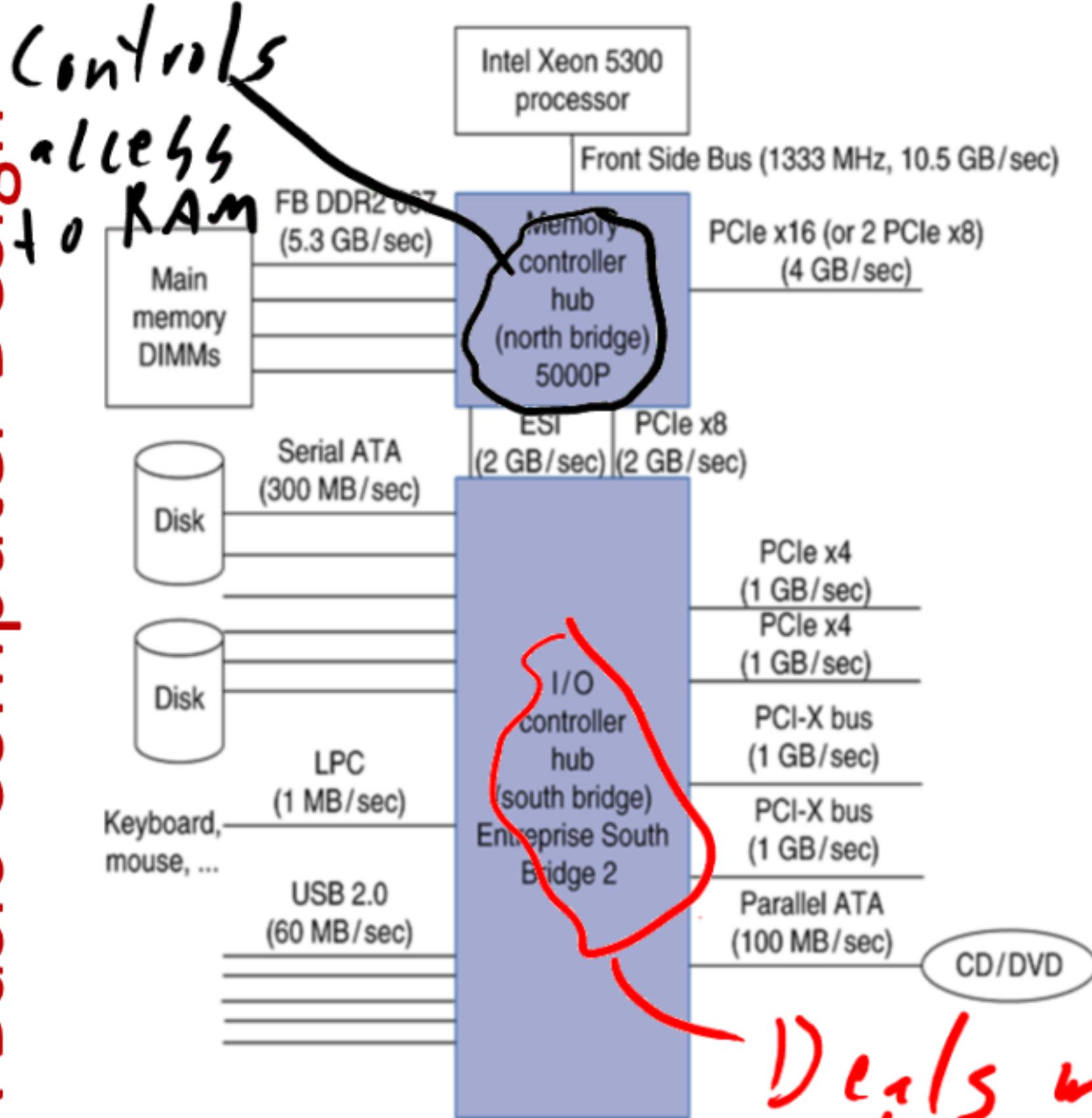
- What does MIMD stand for?

Multiple Instruction
Multiple Data

How would you connect
multiple computers together?

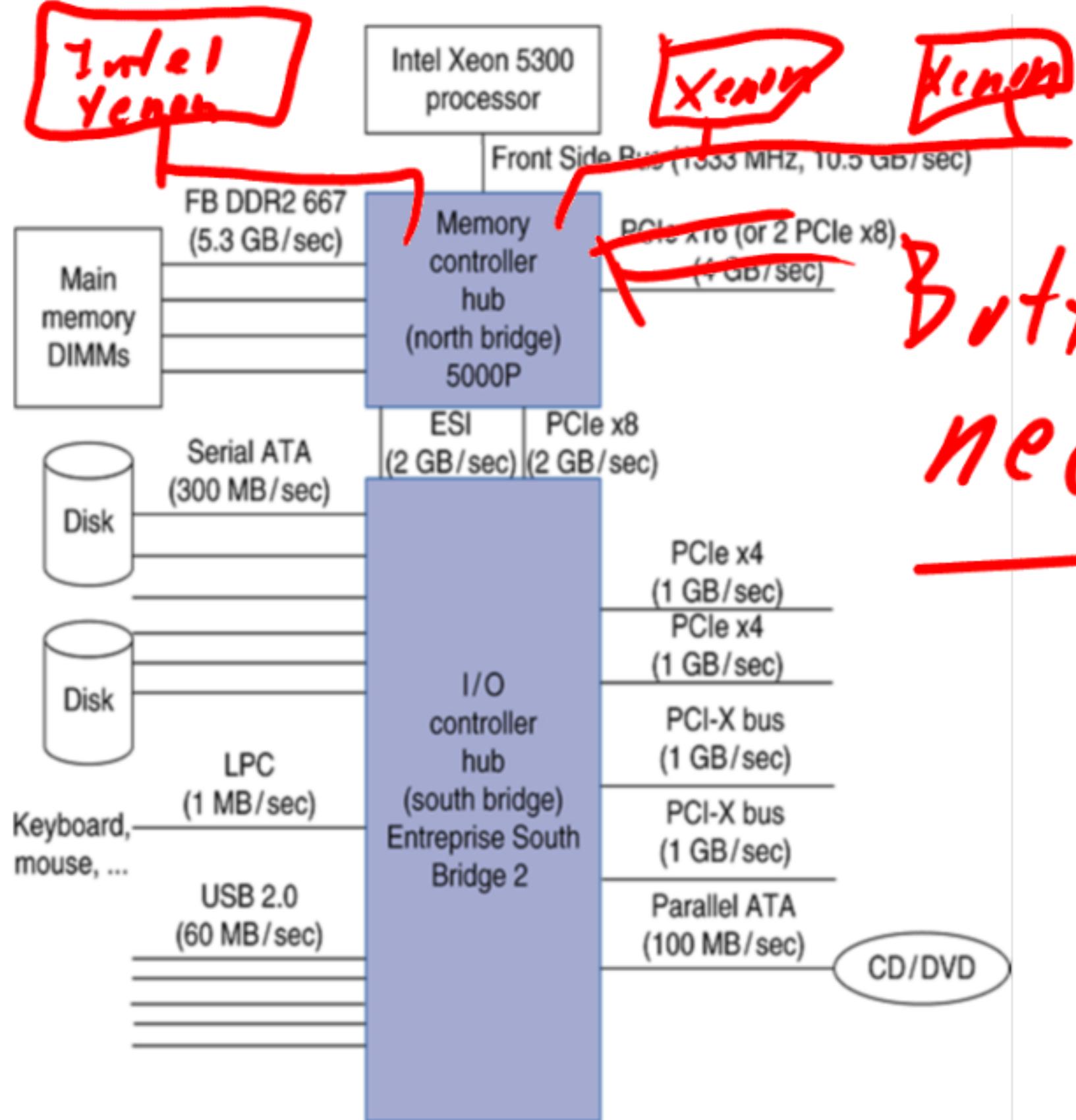


A Basic Computer Design



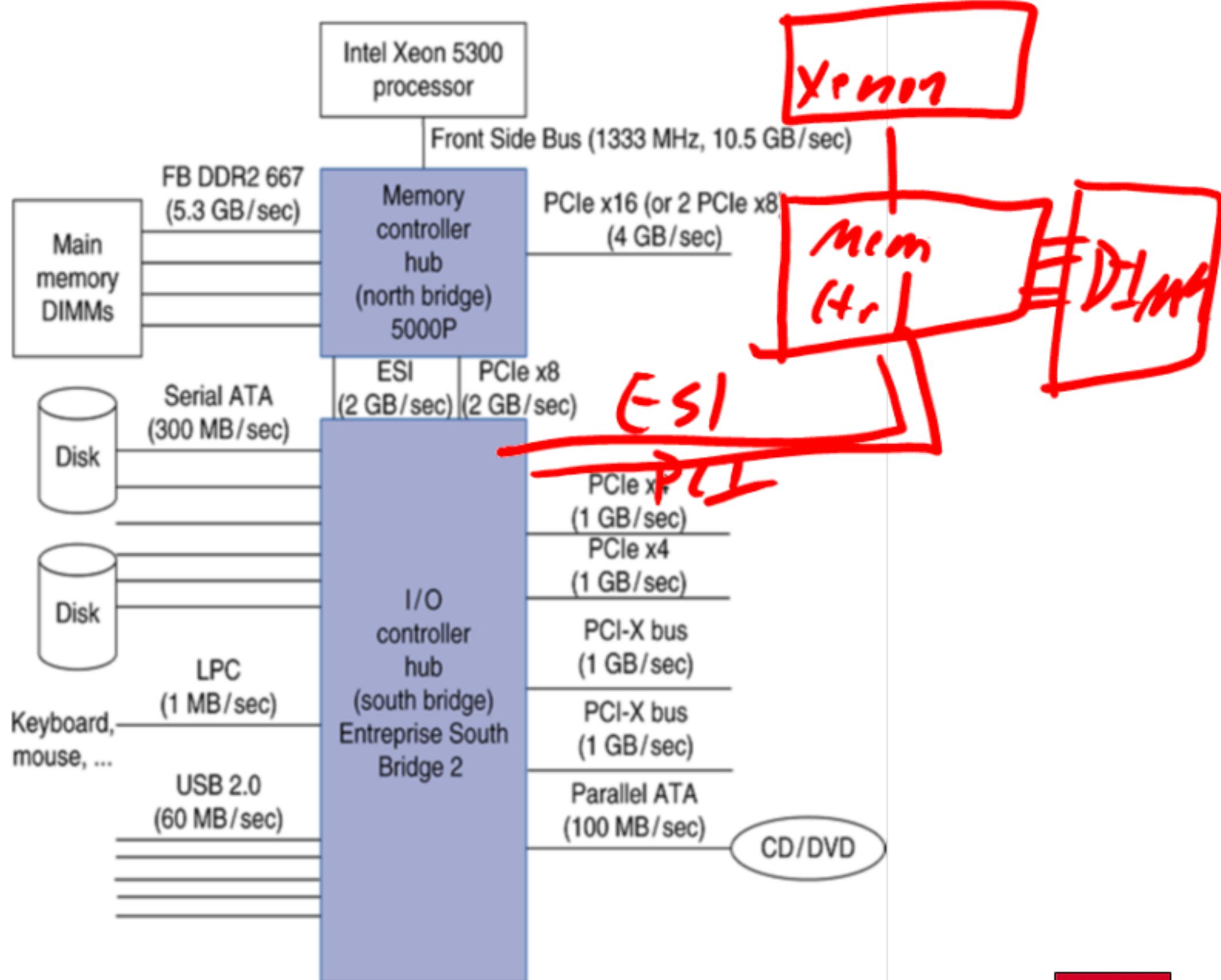
Deals w/
External HW

A Shared Memory System

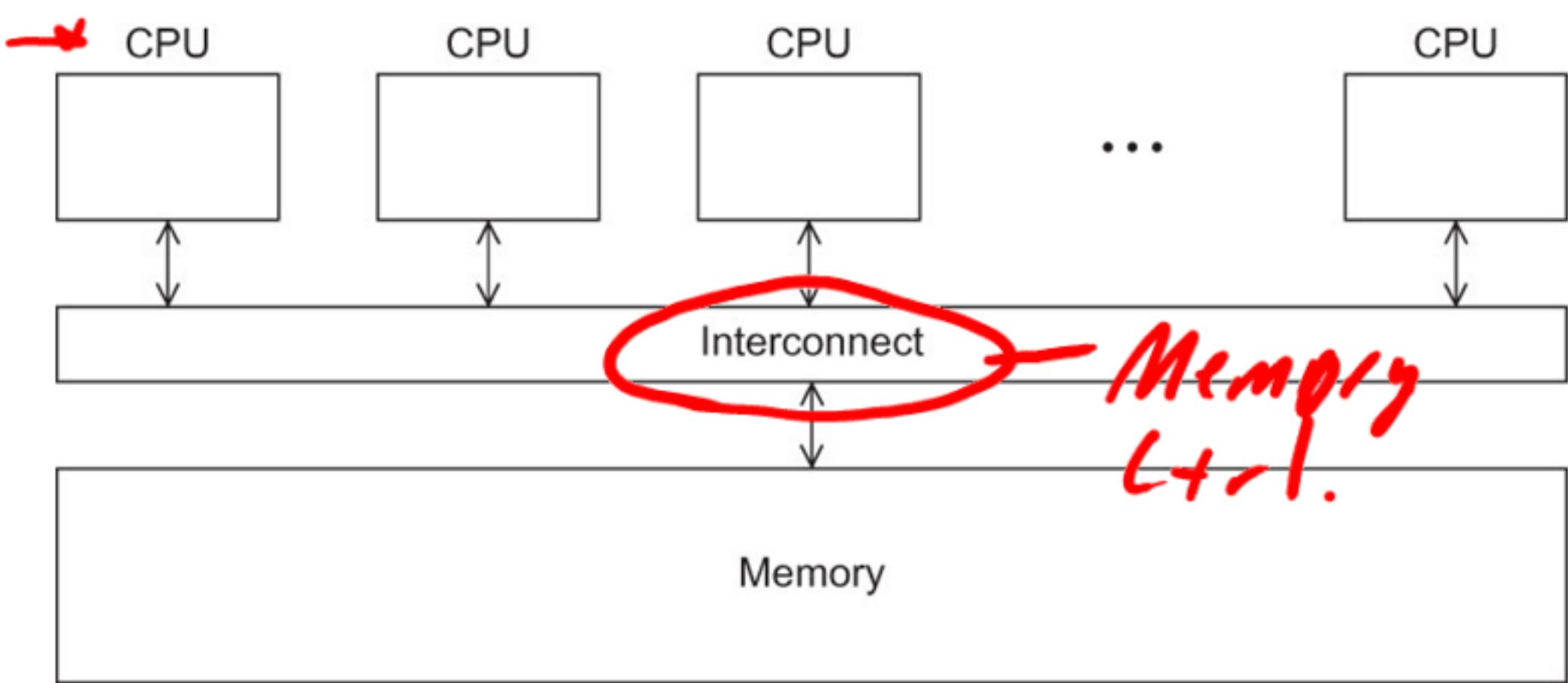


*Patterson and Hennessy: Computer Organization and Design

A Shared Memory System



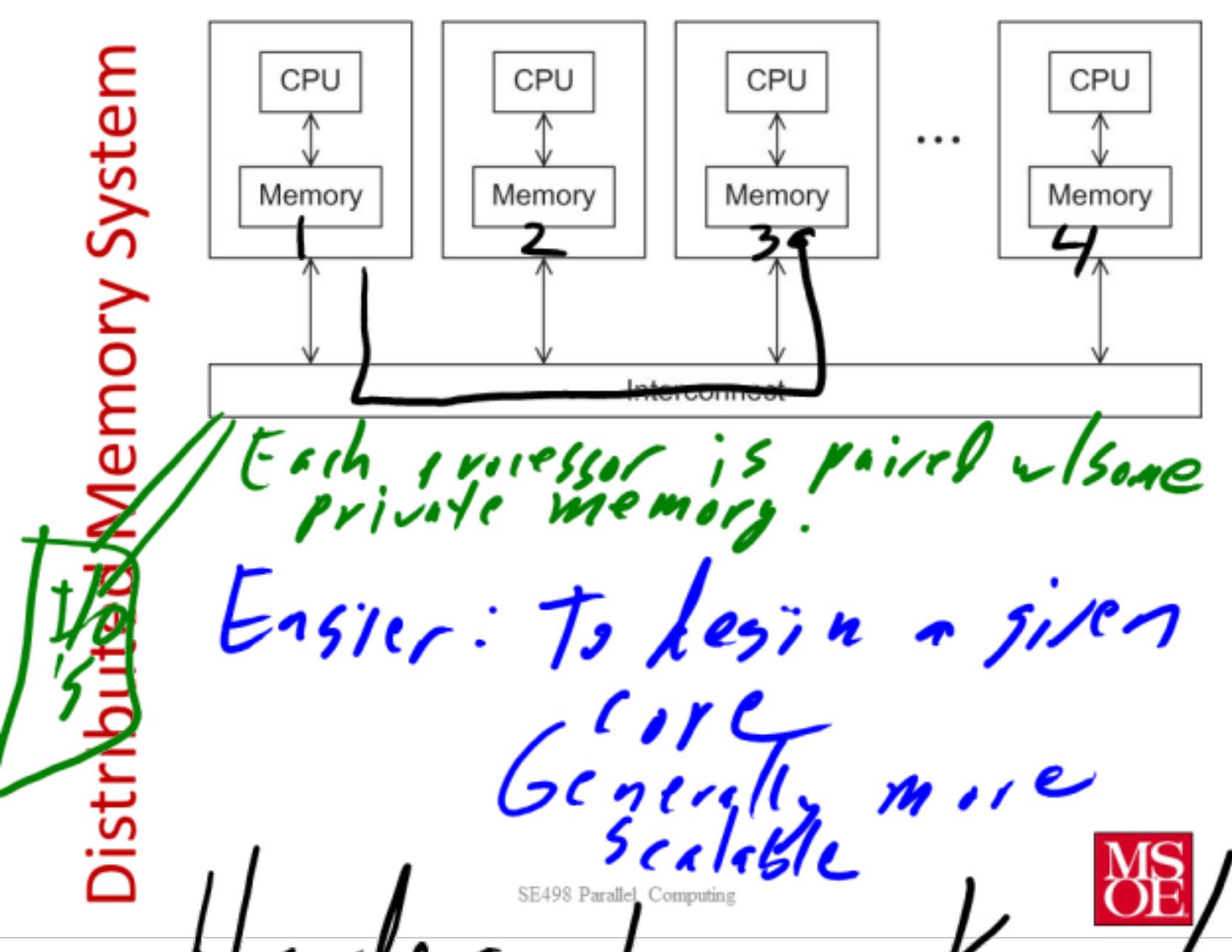
A Refined Shared Memory System



Each processor can access all system memory.
Challenge: Designing the interconnect.

Advantage: less overhead.

Disadvantage: Not as scalable
Hard to build for more than a few



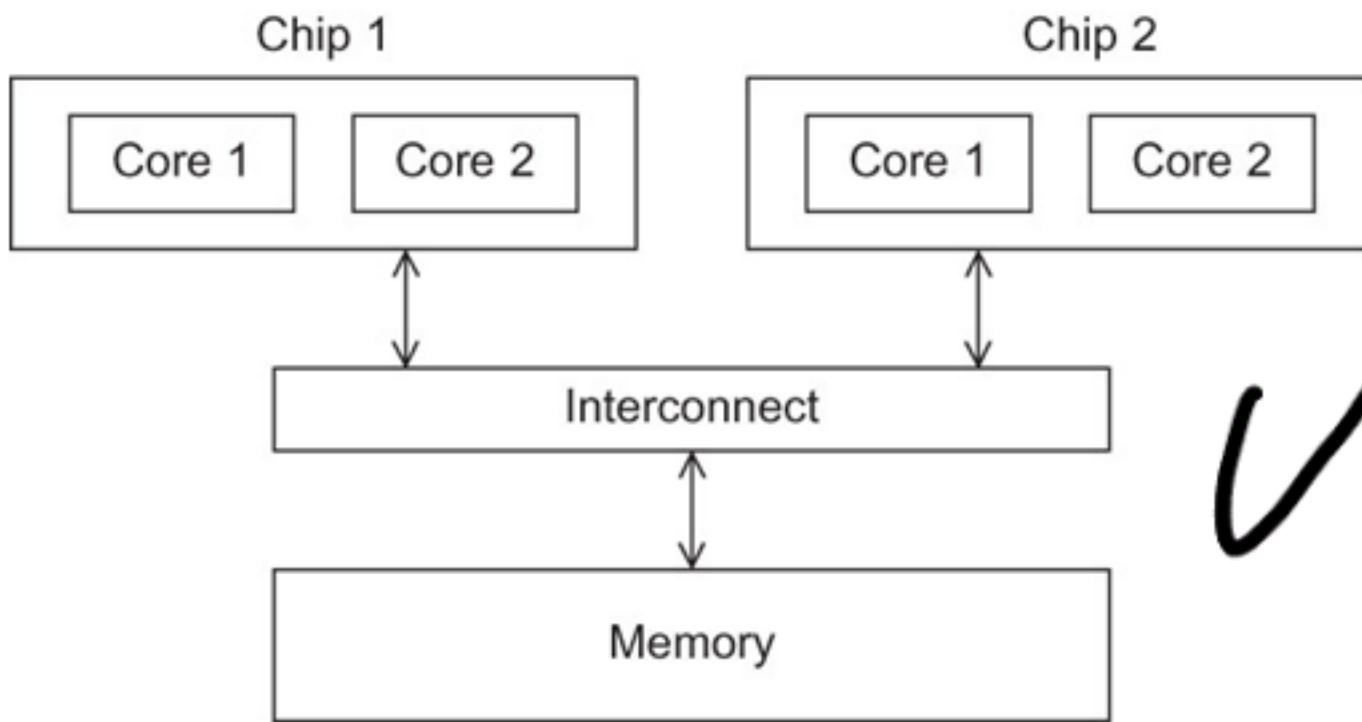
NUMA

Harder to work w/
from a SW standpoint.
May be less performance

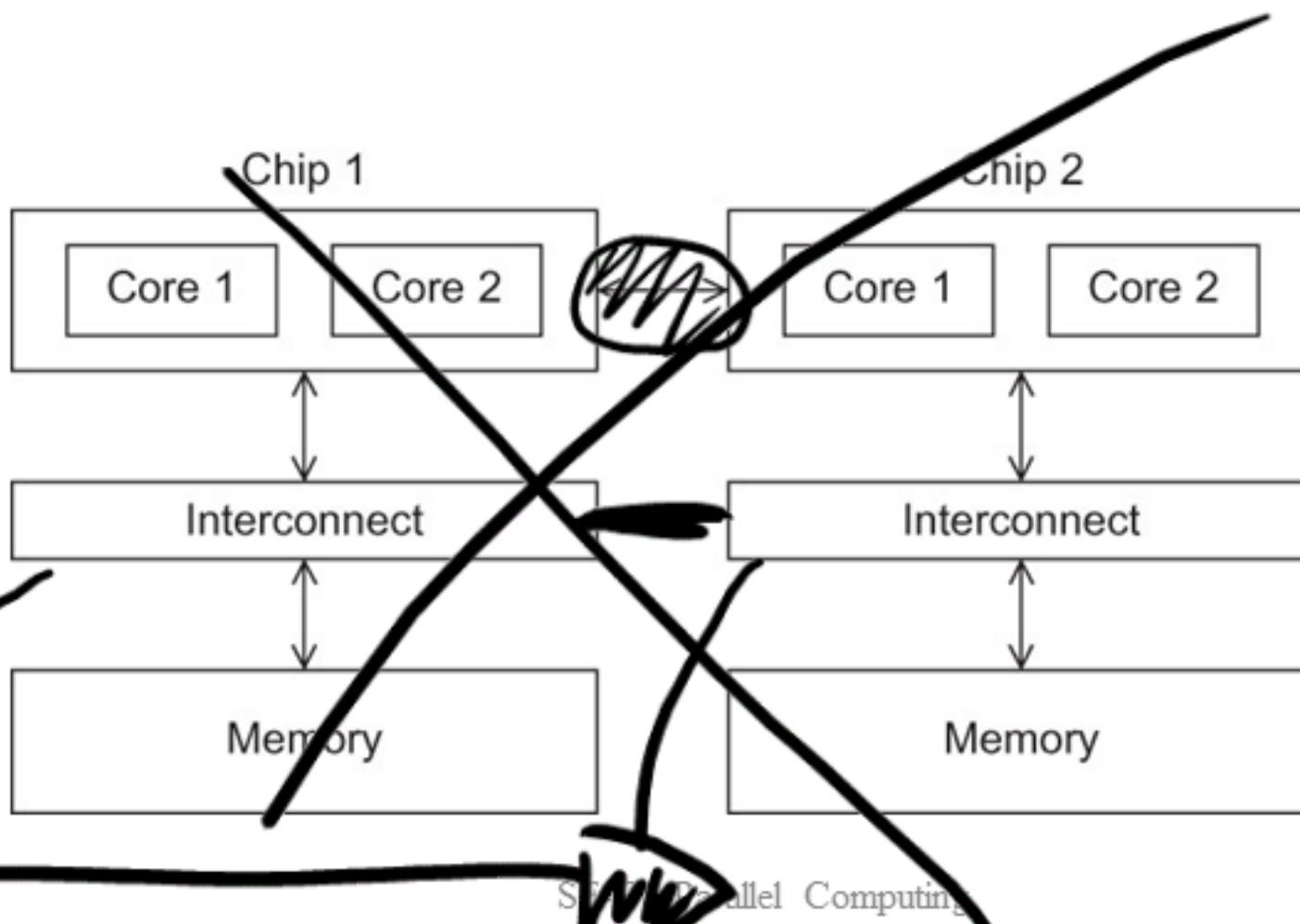
Definitions

- UMA 
 - Uniform Memory Access
 - The access time to all memory is the same, regardless of the processor core's location.
- NUMA
 - Non-Uniform Memory Access 
 - The access time is different depending on where in memory a piece of data is located
- NORMA
 - No Remote Memory Access
 - All memory needed from a remote machine must be requested using a message

Which is which?



VMA



Normal
NUMA

Interconnection Networks

- Very important to have an appropriate interconnection network
 - Slow interconnect will degrade the performance of “perfect” processors

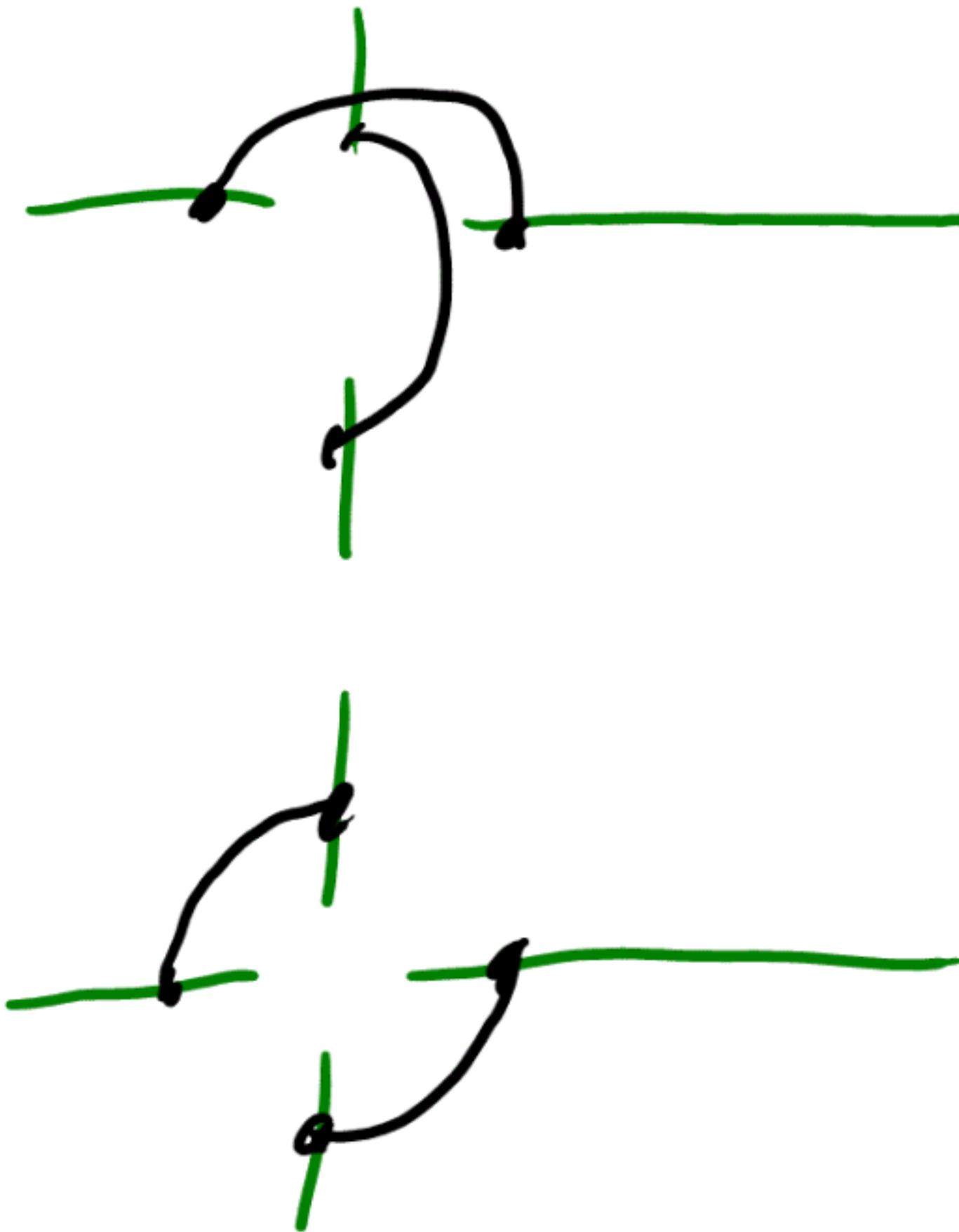


Simple Bus

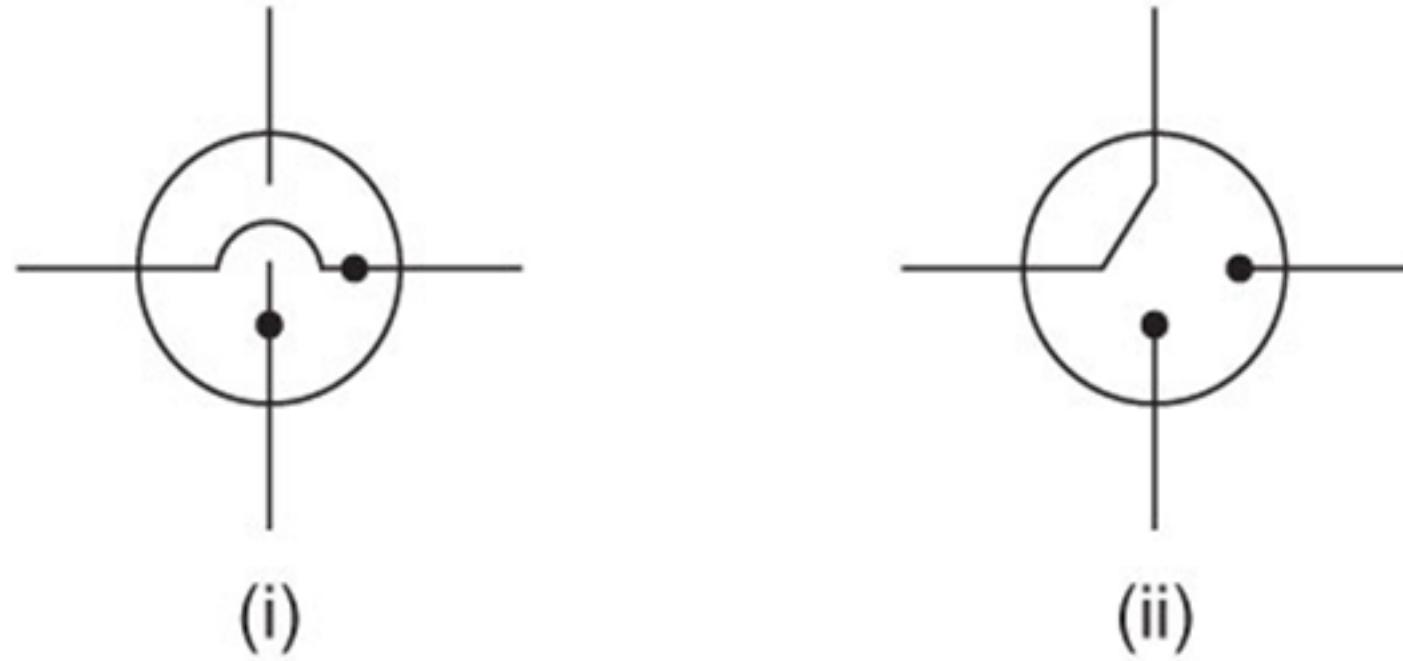
- A set of parallel communication wires between devices
 - Wires are shared by all devices
 - Low cost
 - But
 - If a large number of processors are on the bus, a lot of time will be spent waiting to get the bus.



Switched interconnect (AKA Crossbar)



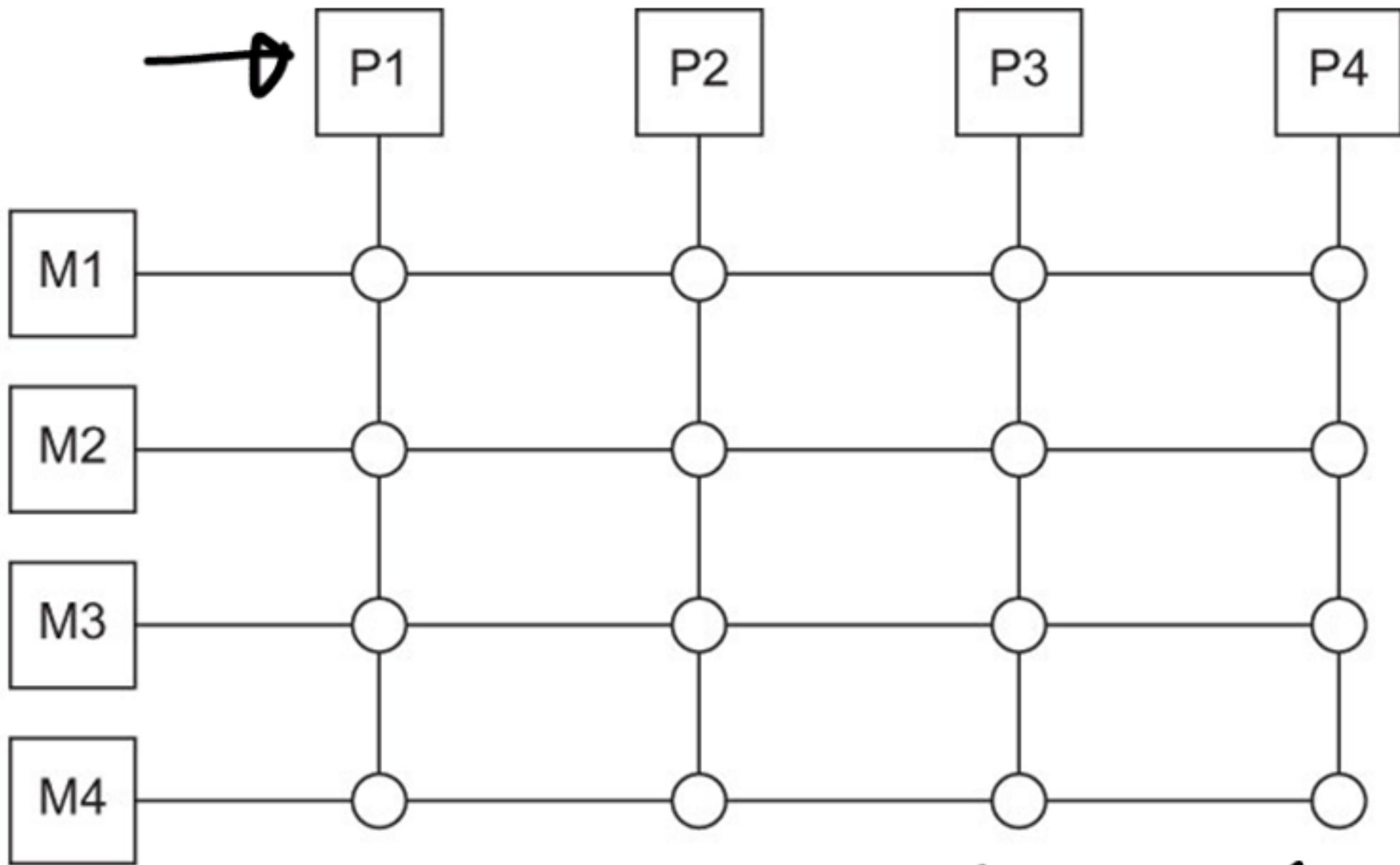
Switched interconnect - Switch



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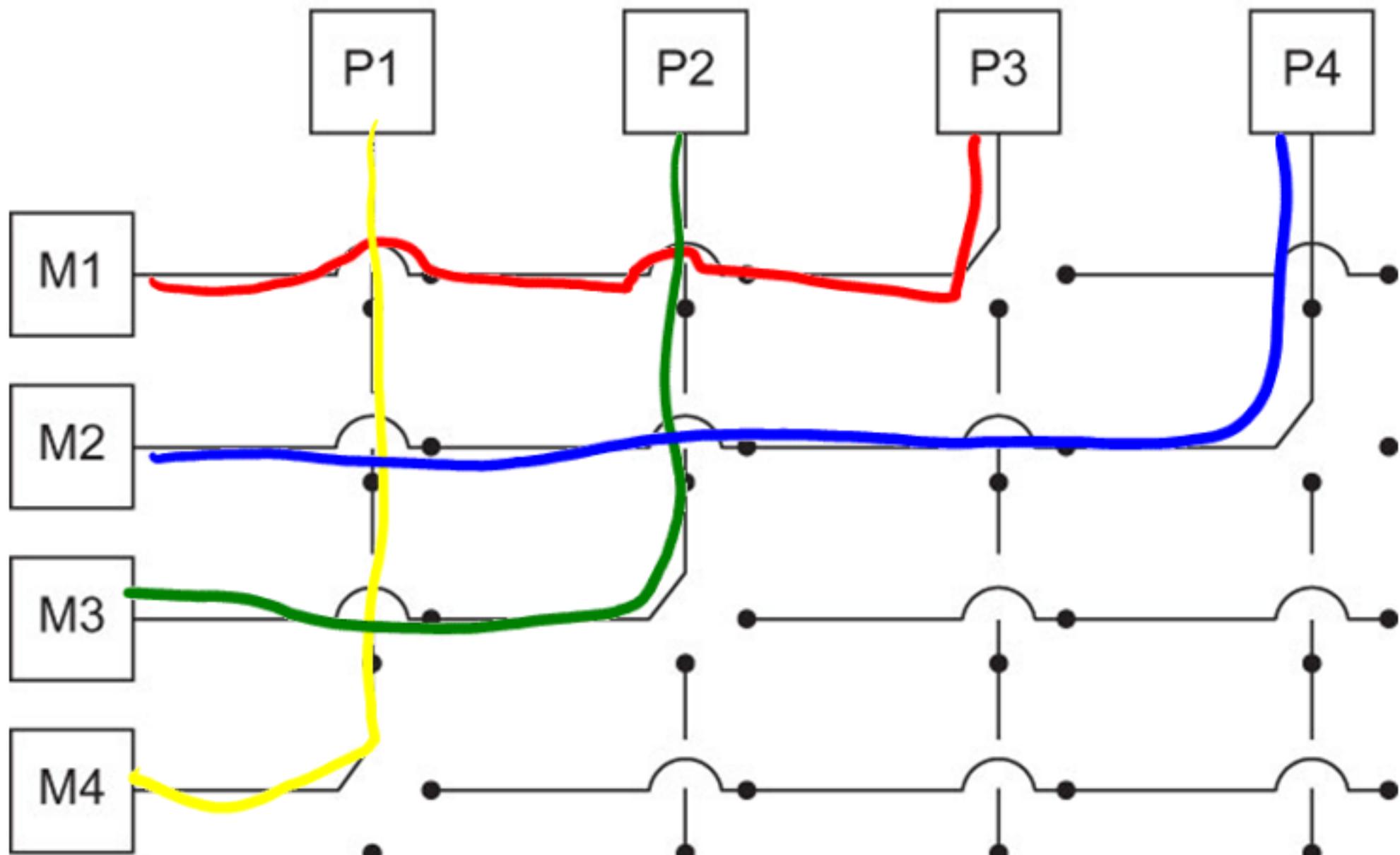
Switched interconnect - Layout

Switched interconnect - Layout



Switched interconnect - Connections

Switched interconnect - Connections



Crossbar Advantages / Disadvantages

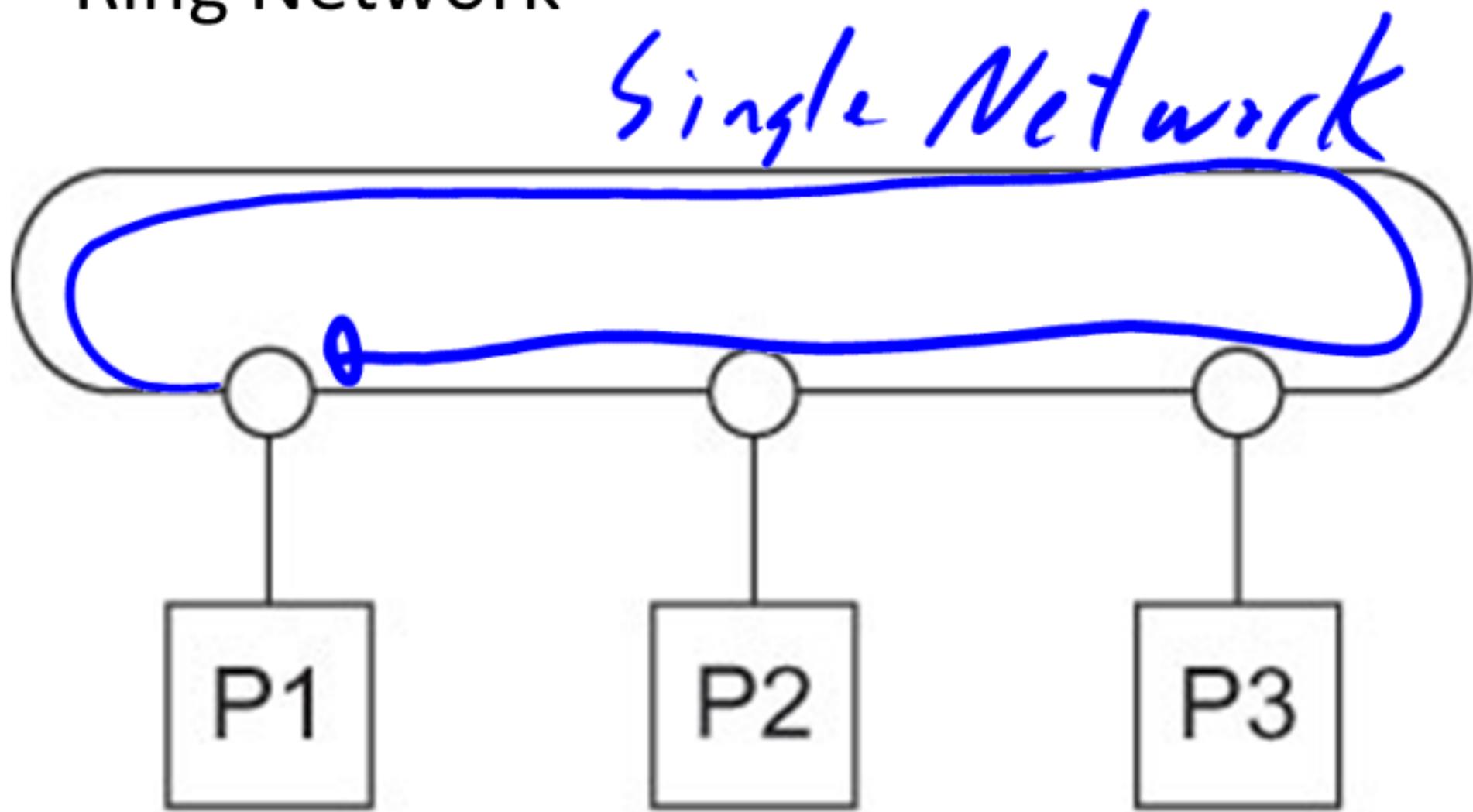
- Advantages
 - Very high performance can be achieved ←
 - Simultaneous communication between devices is possible ←
- Disadvantage
 - Cost of switches is very high ←
 - Complex to design as systems get larger ←

Connecting Distributed Systems

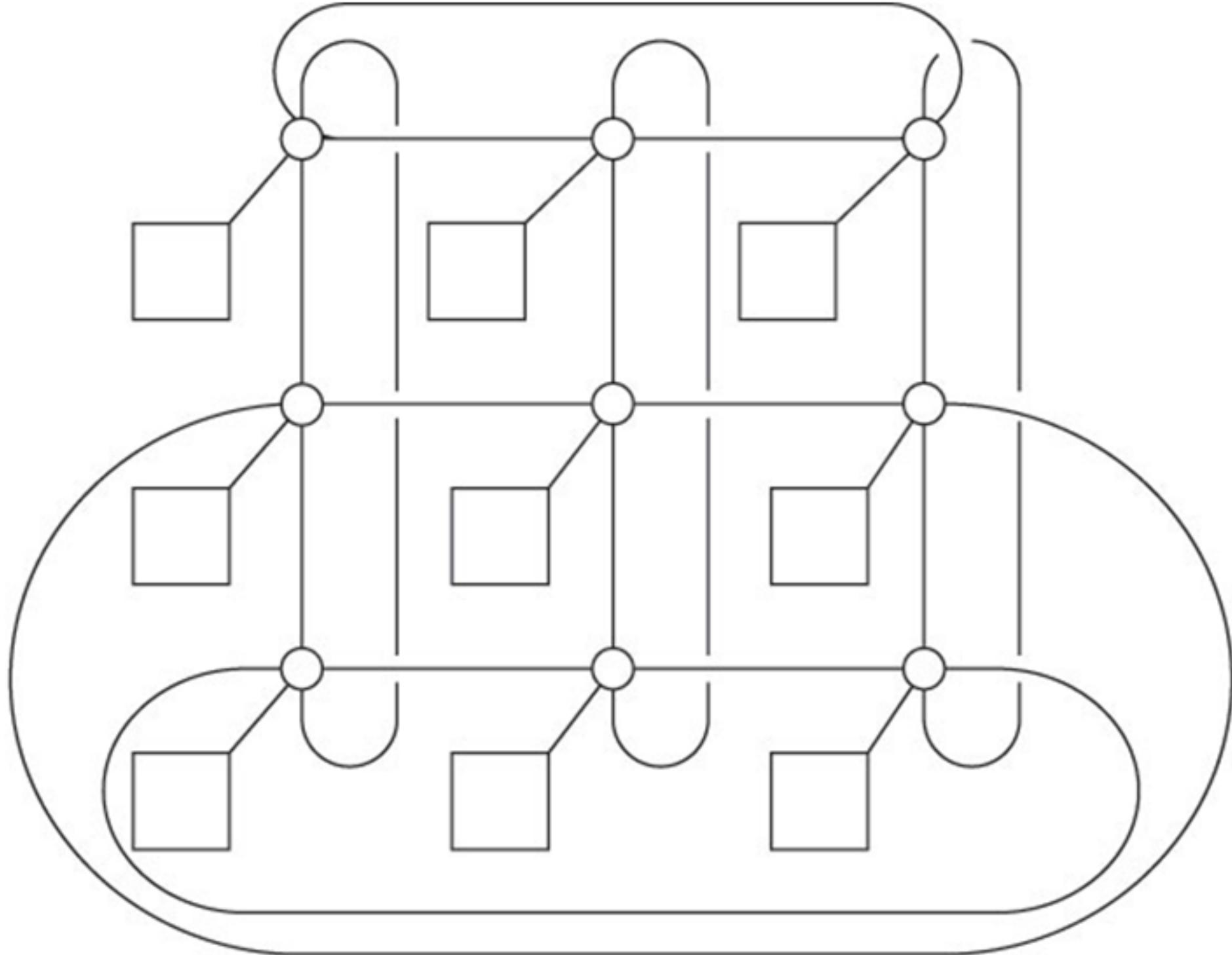
- Ring Network

Connecting Distributed Systems

- Ring Network



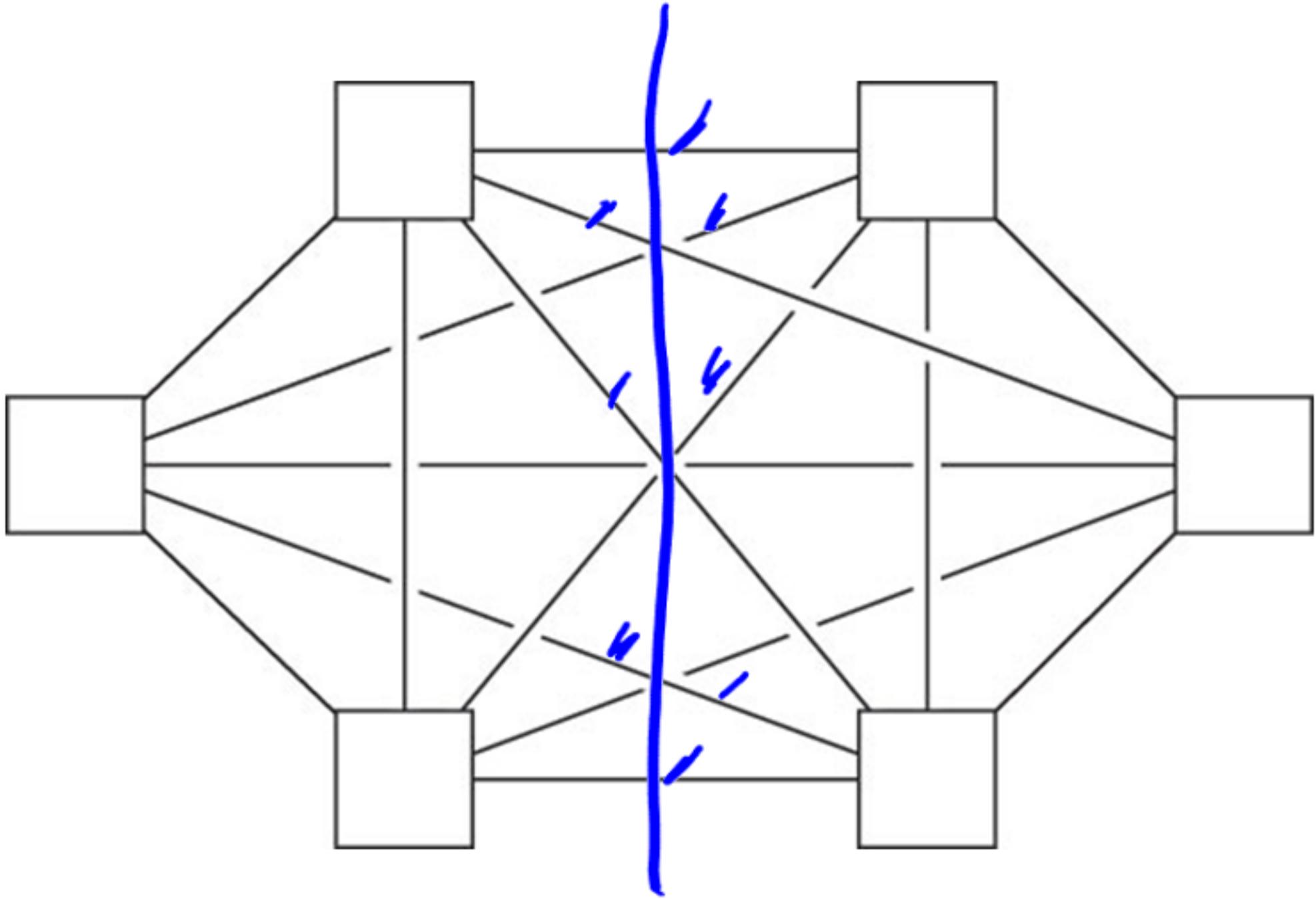
Connecting Distributed Memory Systems – Toroidal Mesh



Definitions

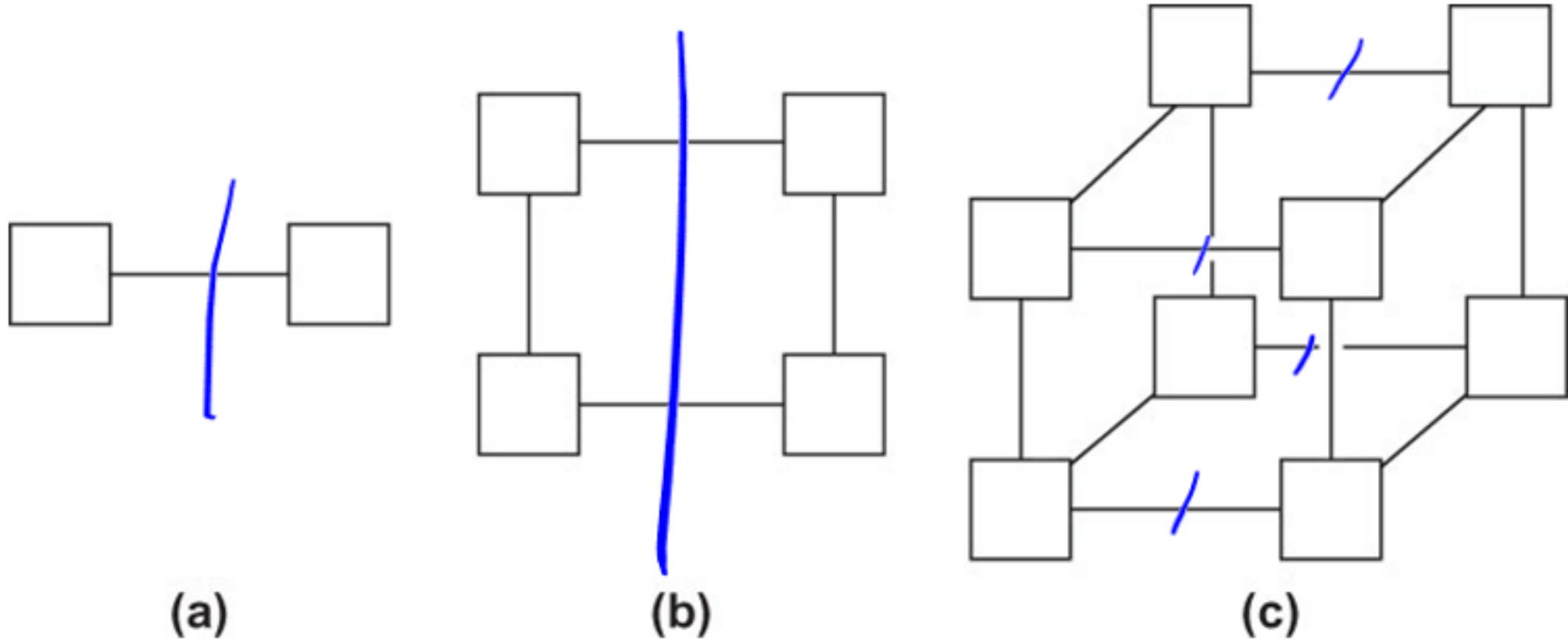
- Diameter
 - The diameter of a network is the largest distance between 2 nodes
- Bisection Width
 - The minimum number of edges that must be removed in order to divide the network into 2 halves
- Bisection Bandwidth
 - The sum of the bandwidth of the bisection width connections

Fully connected network



Diameter - 1
Bisection Bandwidth: 89
Bandwidth: 9 x BW.

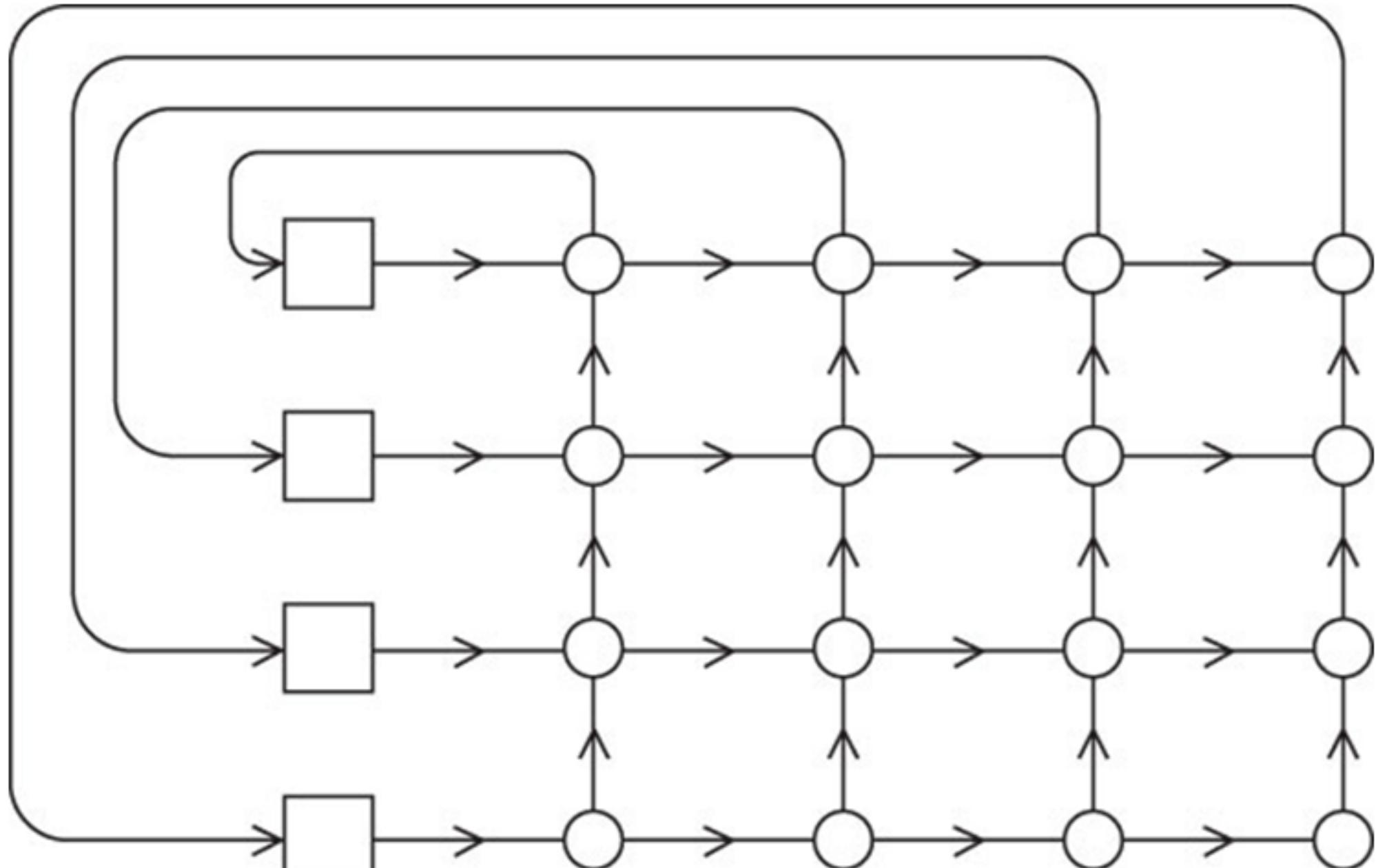
Hypercubes



Hypercube:

Diameter: # of dimensions
Bisection width: # of dimensions
 $\frac{2^d - 1}{2}$

Crossbar Interconnect

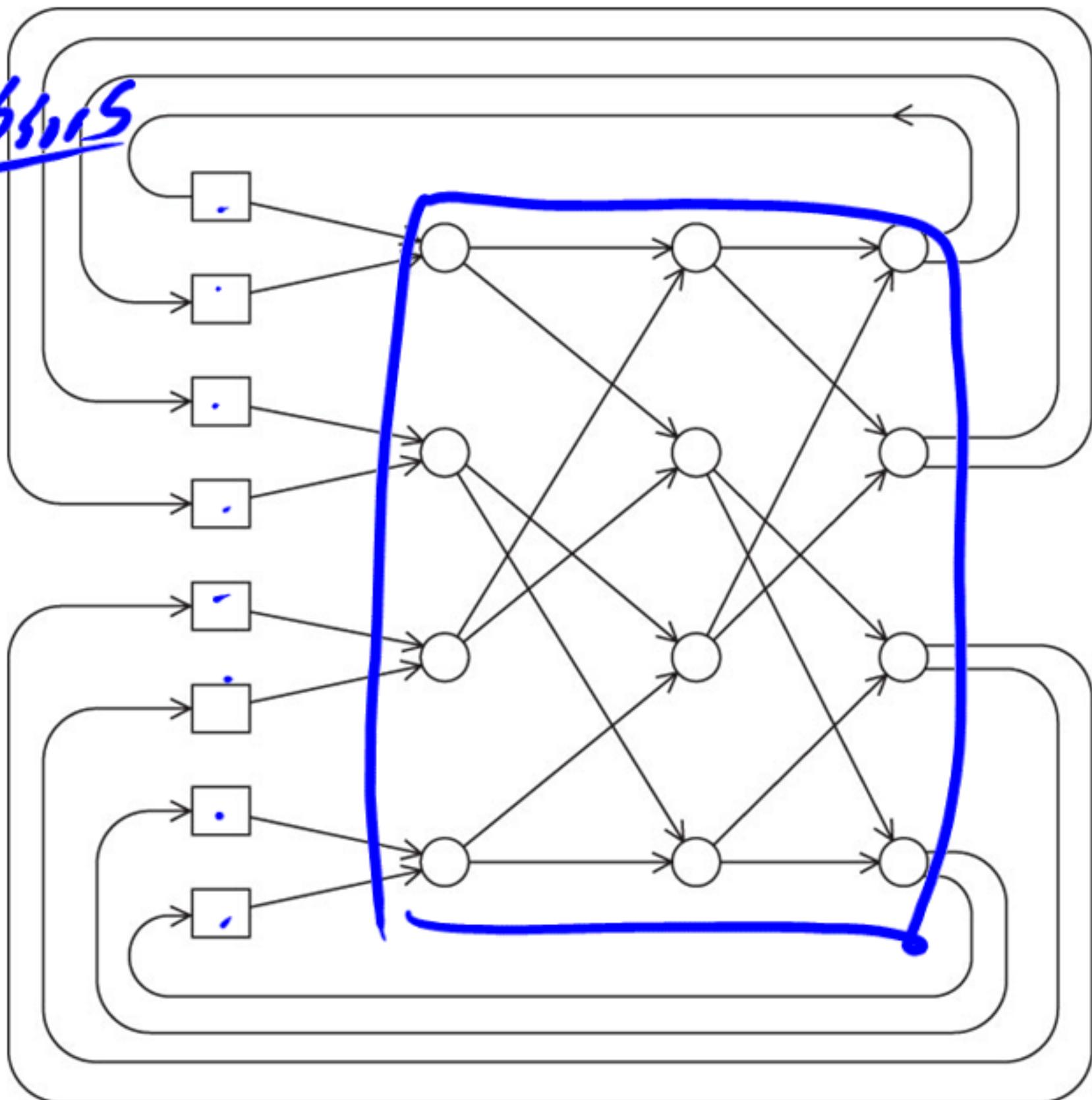


1
Processor/
Memory

1
Switches

Omega Network

8 Processors



Topology Summaries

Network	Nodes	Diameter	Bisection Width
1 D Mesh	K	$k-1$	1
2D Mesh	K^2	$2(k-1)$	K
3D Mesh	K^3	$3(k-1)$	K^2
Binary Tree	$2k-1$	$2(k-1)$	1
Pyramid	$(4k^2-1)/3$	$2k$	$2k$
Hypercube	2^k	$2k-1$	2^{k-1}
Cube Connected Cycle Network	$k2^k$	$2k$	2^{k-1}

Latency and Bandwidth

- Latency → Smaller
 - The time from the source sending the first byte until the destination receives the first byte of a message
 - L – given in seconds – was often smaller
- Bandwidth
 - The rate at which the destination receives data from the source
 - B – bytes per second

$$\text{message Tx Time} = l + \frac{n}{b}$$